# **Autonics**

# • Observe all 'Safety Considerations' for safe and proper operation to avoid hazards.

- ▲ symbol indicates caution due to special circumstances in which hazards may occur.
- **Warning** Failure to follow instructions may result in serious injury or death.
- 01. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss. (e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime / disaster prevention devices, etc.)
- ailure to follow this instruction may result in personal injury, economic loss or fire. 02. Do not use the unit in the place where flammable / explosive / corrosive gas, high humidity, direct sunlight, radiant heat, vibration, impact or salinity may be present.

Failure to follow this instruction may result in explosion or fire. 03. Install on a device panel to use.

Failure to follow this instruction may result in fire.

**Safety Considerations** 

- 04. Do not connect, repair, or inspect the unit while connected to a power source.
- Failure to follow this instruction may result in fire. 05. Check 'Connections' before wiring. Failure to follow this instruction may result in fire.
- 06. Do not disassemble or modify the unit. Failure to follow this instruction may result in fire.

▲ Caution Failure to follow instructions may result in injury or product damage.

- 01. Use the unit within the rated specifications.
- ailure to follow this instruction may result in fire or product damage. 02. Do not short the load.
- ailure to follow this instruction may result in fire. 03. Do not use the unit near the place where there is the equipment which generates strong magnetic force or high frequency noise and strong alkaline, strong acidic exists. Failure to follow this instruction may result in product damage.

### **Cautions during Use**

- Follow instructions in 'Cautions during Use'.
- Otherwise, It may cause unexpected accidents. 5 VDC==, 12 24 VDC== power supply should be insulated and limited voltage / current or Class 2, SELV power supply device.
- · For using the unit with the equipment which generates noise (switching regulator,
- inverter, servo motor, etc.), ground the shield wire to the F.G. terminal. Ground the shield wire to the F.G. terminal.
- When supplying power with SMPS, ground the F.G. terminal and connect the noise canceling capacitor between the 0 V and F.G. terminals.
- · Wire as short as possible and keep away from high voltage lines or power lines, to prevent inductive noise.
- · Check the wire type and response frequency when extending wire because of distortion of waveform or residual voltage increment etc. by line resistance or capacity between lines.
- This unit may be used in the following environments.
- Indoors (in the environment condition rated in 'Specifications') - Altitude max. 2,000 m
- Pollution degree 2
- Installation category II

# 50 mm Diameter Absolute Single-Turn Rotary Encoders (Optical)



# **EP50SP** Series **PRODUCT MANUAL**

#### For your safety, read and follow the considerations written in the instruction manual, other manuals and Autonics website.

The specifications, dimensions, etc. are subject to change without notice for product improvement. Some models may be discontinued without notice.

# **Features**

- Ø50 mm housing, Ø6/Ø8 mm solid shaft
- · Lightweight plastic housing
- Power supply : 5 VDC  $\pm$ 5%, 12-24 VDC  $\pm$ 5%

## **Cautions during Installation**

- Install the unit correctly with the usage environment, location, and the designated specifications.
- Do not load overweight on the shaft.
- Do not put strong impact when insert a coupling into shaft. Failure to follow this instruction may result in product damage.
- When fixing the product or coupling with a wrench, tighten under 0.15 N m.
- If the coupling error (parallel misalignment, angular misalignment) between the shaft increases while installation, the life cycle of the coupling and the encoder can be shorten.
- Do not apply tensile strength over 30 N to the cable.

# **Ordering Information**

This is only for reference, the actual product does not support all combinations. For selecting the specified model, follow the Autonics website.

#### EP50 **0 2 3** -4 -66 0 8

Shaft type

#### Output code 3: Shift Gray Code

the shaft

S: Shaft type O Shaft outer diameter 6:06 mm 8: Ø 8 mm

O Rotating direction

Control output

Power supply

24: 12 - 24 VDC== ±5%

5:5 VDC== ±5%

• Coupling

Bracket

N: NPN open collector output

F: Increase output when the rotating

direction is clockwise base on facing

#### Material

P: Plastic

#### Resolution

Number: Refer to resolution in 'Output Phase / Output Angle'

# **Product Components**

• Product

Instruction manual

## Connections

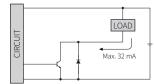
Unused wires must be insulated.

· Since exclusive driver IC is used for output circuit, be aware of short circuits when wiring each output wires. • N · C: not connected

Color	Function	Refer		
White	+V	Power		
Black	GND	Power		
Brown	2 <sup>0</sup>			
Red	2 <sup>1</sup>			
Orange	2 <sup>2</sup>	Output		
Yellow	2 <sup>3</sup>			
Blue	2 <sup>4</sup>			
Purple	2 <sup>5</sup>			
Gray	2 <sup>6</sup>			
White / Brown	2 <sup>7</sup>			
White / Red	2 <sup>8</sup>			
White / Orange	N·C			
Shield	Signal shield			

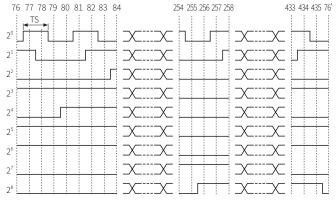
# **Inner Circuit**

• The output circuit is identical for each output bit. • Be aware of circuit break in case of overload or short beyond the specifications.



# **Output Waveform**

• Following waveform is based on the positive logic. (In case of negative logic, the waveform is opposite to corresponding waveform.)



# Specifications

Model	EP50S P- 3F-N-		
Resolution	180, 360-division		
Output code	Shift Gray Code		
Output phase / Output angle	TS (Signal Pulse): 2° ±25′ (9 bit)		
Control output	NPN open collector output		
Inflow current	$\leq$ 15 mA		
Residual voltage	$\leq$ 1 VDC==		
Response speed <sup>01)</sup>	$T_{on} \leq 1 \mu s, T_{off} \leq 1 \mu s$		
Max. response freq.	20 kHz		
Max. allowable revolution <sup>02)</sup>	3,000 rpm		
Starting torque	$\leq$ 0.004 N m		
Inertia moment	$\leq$ 50 g·cm <sup>2</sup> (5 × 10 <sup>-6</sup> kg·m <sup>2</sup> )		
Allowable shaft load	Radial: 2 kgf, Thrust: 1 kgf		
Unit weight (packaged)	≈ 250 g (≈ 308 g)		
Certification	C € 號 EAE		

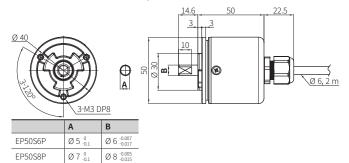
01) Based on cable length: 2 m, I sink = 15 mA

Select resolution to satisfy Max, allowable revolution ≥ Max, response revolution [max, response revolution (rpm)= max, response frequency resolution

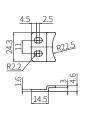
Power supply	5 VDC== ± 5% (ripple P-P: ≤ 5%) / 12 - 24 VDC== ± 5% (ripple P-P: ≤ 5%) model		
Current consumption	$\leq$ 80 mA (no load)		
Insulation resistance	$\geq$ 100 M $\Omega$ (500 VDC== megger)		
Dielectric strength	Between the charging part and the case: 750 VAC $\sim 50$ / 60 Hz for 1 min.		
Vibration	1 mm double amplitude at frequency 10 to 55 Hz in each X, Y, Z direction for 2 hours		
Shock	$\lesssim 50~{ m G}$		
Ambient temp.	-10 to 55 °C, storage: -25 to 85 °C (no freezing or condensation)		
Ambient humi.	35 to 85%RH, storage: 35 to 90%RH (no freezing or condensation)		
Protection rating	IP50 (IEC standard)		
Connection	Axial cable type (cable gland)		
Cable spec.	Ø 6 mm, 12-wire, 2m, shield cable		
Wire spec.	AWG24 (0.08 mm, 40-core), insulator diameter: Ø 1 mm		

# Dimensions

• Unit: mm, For the detailed drawings, follow the Autonics website.



Bracket



Coupling								
$ \begin{array}{c} \mathbf{B} \\ \mathbf{A}_{0}^{*01} \\ \mathbf{C} $								
	А	В	С	D	E			
EP50S6P	Ø 6	Ø 15	2.8	22	4-M3			
EP50S8P	Ø 8	Ø 19	3.4	25	4-M4			
<ul> <li>Parallel misalignment: ≤ 0.25 mm</li> <li>Angular misalignment: ≤ 5°</li> <li>End-play: ≤ 0.5 mm</li> </ul>								