Two-Degree-of-Freedom PID Temperature Controllers

TN Series

INSTRUCTION MANUAL

TCD210227AH

Autonics

Thank you for choosing our Autonics product.

Read and understand the instruction manual and manual thoroughly before using the product.

For your safety, read and follow the below safety considerations before using. For your safety, read and follow the considerations written in the instruction manual, other manuals and Autonics website.

Keep this instruction manual in a place where you can find easily.

The specifications, dimensions, etc are subject to change without notice for product improvement Some models may be discontinued without notice.

Follow Autonics website for the latest information.

Safety Considerations

- Observe all 'Safety Considerations' for safe and proper operation to avoid hazards.
- A symbol indicates caution due to special circumstances in which hazards may occur.

★ Warning Failure to follow instructions may result in serious injury or death

- 01. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss.(e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime/disaster prevention devices, etc.) Failure to follow this instruction may result in personal injury, economic loss or fire.
- 02. Do not use the unit in the place where flammable/explosive/corrosive gas, high humidity, direct sunlight, radiant heat, vibration, impact or salinity

Failure to follow this instruction may result in explosion or fire.

03. Install on a device panel to use.

Failure to follow this instruction may result in electric shock.

04. Do not connect, repair, or inspect the unit while connected to a power

Failure to follow this instruction may result in fire or electric shock.

05. Check 'Connections' before wiring.

Failure to follow this instruction may result in fire.

06. Do not disassemble or modify the unit.

Failure to follow this instruction may result in fire or electric shock.

⚠ Caution Failure to follow instructions may result in injury or product damage

01. When connecting the power input and relay output, use AWG 20 (0.50 mm²) cable or over, and tighten the terminal screw with a tightening torque of 0.74 to 0.90 N m.

When connecting the sensor input and communication cable without dedicated cable, use AWG 28 to 16 cable and tighten the terminal screw with a tightening torque of 0.74 to 0.90 N m.

Failure to follow this instruction may result in fire or malfunction due to contact

02. Use the unit within the rated specifications.

Failure to follow this instruction may result in fire or product damage

- 03. Use a dry cloth to clean the unit, and do not use water or organic solvent. Failure to follow this instruction may result in fire or electric shock
- 04. Keep the product away from metal chip, dust, and wire residue which flow

Failure to follow this instruction may result in fire or product damage.

Cautions during Use

- Follow instructions in 'Cautions during Use'. Otherwise, it may cause unexpected
- Check the polarity of the terminals before wiring the temperature sensor. For RTD temperature sensor, wire it as 3-wire type, using cables in same thickness and length. For thermocouple (TC) temperature sensor, use the designated compensation wire for extending wire.
- Keep away from high voltage lines or power lines to prevent inductive noise. In case installing power line and input signal line closely, use line filter or varistor at power line and shielded wire at input signal line. Do not use near the equipment which generates strong magnetic force or high frequency noise.
- \bullet Do not apply excessive power when connecting or disconnecting the connectors of the product.

- Install a power switch or circuit breaker in the easily accessible place for supplying or disconnecting the power
- Do not use the unit for other purpose (e.g. voltmeter, ammeter), but temperature controller.
- When changing the input sensor, turn off the power first before changing. After changing the input sensor, modify the value of the corresponding parameter
- Do not overlapping communication line and power line. Use twisted pair wire for communication line and connect ferrite bead at each end of line to reduce the effect of external noise
- Make a required space around the unit for radiation of heat. For accurate temperature measurement, warm up the unit over 20 min after turning on the power.
- · Make sure that power supply voltage reaches to the rated voltage within 2 sec after supplying power.
- Do not wire to terminals which are not used.
- This unit may be used in the following environments.
- Indoors (in the environment condition rated in 'Specifications')
- Altitude Max. 2,000 m
- Pollution degree 2
- Installation category II

Ordering Information

This is only for reference, the actual product does not support all combinations. For selecting the specified model, follow the Autonics website.

T N O - O O O O O O O O	T N	0	-	0	8	4	Θ	0	-	0	8	-	9	
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Size

S: DIN W 48 \times H 48 mm H: DIN W 48 × H 96 mm

1: DIN W 96 × H 96 mm 2 Control method

No mark: Fixed control P: Program control

O Power supply

4: 100 - 240 VAC Alarm outputs

2: Alarm 1 / 2 4: Alarm 1/2/3/4 6: Alarm 1/2/3/4/5/6

Control output 1

R: Relay S: SSR drive

C: Current or SSR drive

Manual

For proper use of the product, refer to the manuals and be sure to follow the safety

Download the manuals from the Autonics website

Software

Download the installation file and the manuals from the Autonics website.

DAQMaster is comprehensive device management program. It is available for

Product Components

• Product (+ bracket)

Sold Separately

- Front cover: FSA / FHA / FLA-COVER
- Current transformer (CT)
- Terminal protection cover: RSA / RMA / RHA / RLA-COVER
- Communication Converter: SCM-USP / SCM-38I / SCM-US48I / SCM-WF48

Power supply 100 - 240 VAC∼, 50/60 Hz Permissible voltage range 90 to 110 % of rated voltage ≤ 8 VA Display type 11 segment, LCD type (operating value display part: 7 segment 50 / 100 / 250 ms (parameter) Sampling period Input specification Refer to 'Input Type and Using Range' • 0.0-50.0 A (primary current measurement range) • CT ratio: 1/1,000

• Contact - ON: $\leq 2 \text{ k}\Omega$, OFF: $\geq 90 \text{ k}\Omega$ Non contact - residual voltage ≤ 1.0 V, leakage current ≤ 0.1 mA Digital • Outflow current: ≈ 0.5 mA per input 250 VAC∼ 3A 1a Contro 12 VDC= ± 2 V, ≤ 20 mA

• Measurement accuracy: ±5% F.S. ±1digit

DC 0 - 20 mA or DC 4 - 20 mA (parameter), Load resistance: ≤ Current 250 VAC~ 3 A 1a Alarm

DC 4 - 20 mA (load resistance: \leq 500 Ω , output accuracy: \pm 0.3% ransmission output Communication RS485 ON/OFF, P, PI, PD, PID

• Thermocouple, RTD: 1 to 100 (0.1 to 100.0) °C/°F • Analog: 1 to 100 digit

• Selectable current or SSR drive output: 1.0 to 120.0 sec

0.75 mm amplitude at frequency of 5 to 55 Hz in each X, Y, Z

Double insulation or reinforced insulation (mark: 🗉, dielectric

strength between the measuring input part and the power part:

 ± 2 kV square shaped noise by noise simulator (pulse width: 1 μ s)

-10 to 50 °C, storage: -20 to 60 °C (no freezing or condensation)

• TNH, TNL: front side

≈ 10 years (non-volatile semiconductor memory type)

•TNS: \approx 128 g (\approx 156 g) •TNH: \approx 184 g (\approx 286 g) •TNL: \approx 301 g (\approx 443 g)

0.1 to 999.9 °C (0.1 to 999.9%)

3,000 VAC ~ 50/60 Hz for 1 min

• OUT1/2: ≥ 5,000,000 operations

OUT1/2: ≥ 200,000 operations

 \geq 100 M Ω (500 VDC= megger)

IP65 (Front panel, IEC standards)

irection for 2 hours

R-phase, S-phase

5 to 85%RH

• TNS: top side

Relay / SSRP output: 0.1 to 120.0 sec

Between the charging part and the case:

AL1/2/3/4/5/6: $\geq 20,000,000$ operations

• AL1/2/3/4/5/6: \geq 100,000 operations

Multi SV ≤ 4 SV Contro roup PID ≤ 8 group 7one PID 4 zones ARW (Anti Re

Time setting

0 to 9,999 sec

0 to 9,999 sec

0.0 to 100.0%

Setting type

Mechanical

Electrical

50 to 200 % Windup) ≤ 10 patterns Program C: Current or SSR drive Program ≤ 200 steps (1 pattern: ≤ 20 steps) Step

Hysteresis

Integral time (I)

Derivative time (D)

Control cycle (T)

Dielectric strength

Insulation resistance

Insulation type

Noise immunity

Memory retention

Protection structure

Loader port

Certification

Ambient temperature

Unit weight (packaged)

Communication Interface

Manual reset

Vibration

Relay life

cycle

Proportional band (P)

Option

Specifications

Communication

N: None R: RS485

R: Relav

S: SSR drive

Terminal type

3 Control output 2

9 Option input/output

No.	Digital input	CT input	Transmission output
006	0	1	0
800	2	1	0
009	3	1	0
014	3	2	0
026	0	1	1
031	0	2	1

considerations in the manuals.

parameter setting, monitoring.

Instruction manual

■ RS485

Comm. protocol	Modbus RTU/ASCII, Sync-Master, PLC ladderless
Connection type	RS-485, RS-422A
Application standard	EIA RS485 compliance with
Maximum connection	32 units (address: 01 to 99)
Synchronous method	Asynchronous
Comm. Method	Two-wire half duplex
Comm. effective range	≤ 800 m
Comm. speed	≤ 115,200 bps
Response time	5 to 99 ms (default: 20 ms)
Start bit	1 bit (fixed)
Data bit	8 bit (fixed)
Parity bit	None (default), Odd, Even
Stop bit	1 bit, 2 bit (default)
EEPROM life cycle	≈ 1,000,000 operations (Erase / Write)

^{• 1} character of ModBus RTU is fixed at 11 bit

Input Type and Using Range

The setting range of some parameters is limited when using the decimal point display.

Input type	e	Decimal point	Display	Using range (°C)	Using range (°F)
	14 (CA)	1	K E R.H	-200 to 1,350	-328 to 2,462
	K (CA)	0.1	K E R.L	-199.9 to 999.9	-199.9 to 999.9
	1 (10)	1	JI E.H	-200 to 800	-328 to 1,472
	J (IC)	0.1	JI C.L	-199.9 to 800.0	-199.9 to 999.9
	E (CR)	1	E C R.H	-200 to 800	-328 to 1,472
	E (CR)	0.1	E C R.L	-199.9 to 800.0	-199.9 to 999.9
	T (CC)	1	E C C.H	-200 to 400	-328 to 752
	1 (CC)	0.1	E C C.L	-199.9 to 400.0	-199.9 to 752.0
	B (PR)	1	ь РР	0 to 1,800	32 to 3,272
Th	R (PR)	1	R PR	0 to 1,750	32 to 3,182
Thermo -couple	S (PR)	1	S PR	0 to 1,750	32 to 3,182
-couple	N (NN)	1	n nn	-200 to 1,300	-328 to 2,372
	C (TT) 01)	1	[EE	0 to 2,300	32 to 4,172
	G (TT) 02)	1	G EE	0 to 2,300	32 to 4,172
	L (IC)	1	LI C.H	-200 to 900	-328 to 1,652
	L (IC)	0.1	LI C.L	-199.9 to 900.0	-199.9 to 999.9
	U (CC)	1	∪С С.Н	-200 to 400	-328 to 752
	0 (CC)	0.1	U C C.L	-199.9 to 400.0	-199.9 to 752.0
	Platinel II	1	PLII	0 to 1,390	32 to 2,534
	L (RUS)	1	L R.H	-200 to 800	-328 to 1,472
		0.1	L R.L	-199.9 to 800.0	-199.9 to 999.9
	Cu50 Ω	0.1	CU 5	-199.9 to 200.0	-199.9 to 392.0
	Cu100 Ω	0.1	C U 10	-199.9 to 200.0	-199.9 to 392.0
	JPt100 Ω	1	JPE.H	-200 to 650	-328 to 1,202
RTD	JF1100 12	0.1	JPE.L	-199.9 to 650.0	-199.9 to 999.9
KID	DPt50 Ω	0.1	dPt5	-199.9 to 600.0	-199.9 to 999.9
	DPt100 Ω	1	dPE.H	-200 to 650	-328 to 1,202
	DF (100 12	0.1	dPt.L	-199.9 to 650.0	-199.9 to 999.9
	Nickel120 Ω	1	NI 15	-80 to 260	-112 to 500
	0 to 10 V	-	AV I	0 to	10 V
	0 to 5 V	-	AV2	0 to	5 V
Analog	1 to 5 V	-	AV3	1 to	5 V
Allalog	0 to 100 mV	-	AMV I	0 to	100 mV
	0 to 20 mA	-	AMA I	0 to	20 mA
	4 to 20 mA	-	AWA5	4 to	20 mA
Permissible	line resistance per	line: ≤ 5 Ω			

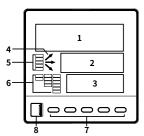
⁰¹⁾ C (TT): Same as existing W5 (TT) type sensor

■ Display accuracy

Input type	Using temperature	Display accuracy
Thermo -couple	At room temperature (23°C ±5°C)	$ \begin{array}{l} (\text{PV}\pm0.2\% \text{ or }\pm1^{\circ}\text{C higher one})\pm1\text{-digit} \\ \bullet \text{Thermocouple K, J, T, N, E below -100^{\circ}\text{C and L, U, PLII,} \\ \text{RTD Cu50}\Omega, \text{DPt50}\Omega\text{: }(\text{PV}\pm0.3\% \text{ or }\pm2^{\circ}\text{C higher one}) \\ \pm1\text{-digit} \\ \bullet \text{Thermocouple C, G and R, S below 200^{\circ}\text{C:}} \\ (\text{PV}\pm0.3\% \text{ or }\pm3^{\circ}\text{C higher one}) \\ \pm1\text{-digit} \\ \bullet \text{Thermocouple B below 400^{\circ}\text{C:}} \\ \text{There is no accuracy standards} \\ \end{array} $
RTD	Out of room temperature range	$ \begin{array}{l} (\text{PV}\pm0.5\% \text{ or } \pm 2^{\circ}\text{C higher one}) \pm 1\text{-digit} \\ \bullet \text{RTD Cu50 } \Omega, \text{DPt50 } \Omega : (\text{PV}\pm0.5\% \text{ or } \pm 3^{\circ}\text{C higher one}) \\ \pm 1\text{-digit} \\ \bullet \text{Thermocouple R, S, B, C, G:} \\ (\text{PV}\pm0.5\% \text{ or } \pm 5^{\circ}\text{C higher one}) \pm 1\text{-digit} \\ \bullet \text{Other sensors:} \leq \pm 5^{\circ}\text{C } (\leq -100^{\circ}\text{C}) \end{array} $
A	At room temperature (23°C ±5°C)	±0.2% F.S. ±1-digit
Analog	Out of room temperature range	±0.5% F.S. ±1-digit

Unit Descriptions

- Below is based on TNL Series.
- The shape and function of each part may be different depending on the series, and it is possible to check the additional information in the user manual.



1. PV display part (White)

• Setting mode: Displays parameter name

2. SV display part (Green)

- Setting mode: Displays parameter setting value. 3. Operating value display part (Yellow)
- (Manipulated output value), P/S, TM, CT with

4. Temperature control indicator

- Fixed control: Relative PV value status display based on SV
- $PV > SV (\nearrow), PV = SV (\rightarrow), PV < SV (\searrow)$
- status of up (\nearrow) , hold (\rightarrow) , down (\searrow) .

5. Operation status indicator

PROG Program Turns ON during program control. WAIT Wait Turns ON during waiting status.	Display	Name	Description		
WAIT Wait Turns ON during waiting status.	LOCK	Lock	Turns ON during key lock status.		
	PROG	Program			
	WAIT	Wait	Turns ON during waiting status.		
HBA1/2 Heater break Turns ON when the heater break alarm output is ON.	HBA1/2	Heater break alarm	Turns ON when the heater break alarm output is ON.		

6 Output status indicator

Display	Name	Description			
OUT1/2	Control output	Turns ON when the control output is ON			
AT	Auto tuning	Flashes during auto tuning every 1 sec			
MAN	Manual control	Turns ON during manual control mode			
STOP	Control output stop	Turns ON during control output stop mode			
HOLD	Program control hold	Turns ON when program control is hold status			
AL1 to 6	Alarm output	Turns ON when the alarm output is ON			

• RUN mode: Displays PV (Present value) and unit.

- · RUN mode: Displays SV (Setting value) and unit.
- RUN mode: Displays selected value among MV

- Program control: Displays temperature control

7. Input key						
Display	Name					
[U]	User key					
[M]	Mode key					
$[\blacktriangleleft], [\blacktriangledown], [\blacktriangle]$	Setting value control key					

8. PC loader port

For connecting communication converter (SCM-USP).

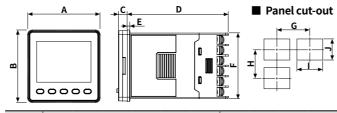
Errors

Display	Input	Description	Output	Troubleshooting	
OPEN	Temperature sensor	Flashes at 0.5 sec interval when input sensor is disconnected or sensor is not connected.	'Sensor error, MV' parameter setting value	Check input sensor status.	
	Analog	Flashes at 0.5 sec interval when input is over F.S. $\pm 10\%$.	'Sensor error, MV' parameter setting value	Check analog input status.	
0000	Temperature sensor	Flashes at 0.5 sec interval if the input value is above the input range. (1)	Heating: 0%, Cooling: 100%		
LLLL	Analog	Flashes at 0.5 sec interval if the input value is over 5 to 10% of high limit or low limit value.	Normal output	When input is within the rated	
	Temperature sensor	Flashes at 0.5 sec. interval if the input value is below the input range. (1)	Heating: 100%, Cooling: 0%	input range, this display disappears.	
	Analog	Flashes at 0.5 sec interval if the input value is over 5 to 10% of low limit or high limit value.	Normal output		
ERR	-	Flashes at 0.5 sec interval if there is error for setting and it returns to the error-before screen.	-	Check setting method.	
Ŀ MR.E	-	Flashes twice and stops operation at the start of operation if the timer operation related parameter setting is not completed.	'STOP, MV' parameter setting value	Set the timer operation related parameters.	
P E N.E	-	Flashes twice and stops operation at the start of operation if the program operation related parameter setting is not completed.	'STOP, MV' parameter setting value	Set the program operation related parameters.	
E R.□□	-	Flashes twice the address of failed Slave when using Sync communication or PLC setting copy function.	-	Check the failed slave connection status and communication settings.	

⁰¹⁾ Be careful that when HHHH / LLLL error occurs, the control output may occur by recognizing the

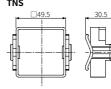
Dimensions

- Unit: mm, For the detailed drawings, follow the Autonics website.
- Below is based on TNS Series.



	Body	Body					Panel cut-out			
	Α	В	С	D	E	F	G	Н	I	J
TNS	49	49	6	69	1.5	44.8	≥ 65	≥ 65	45 ^{+0.6}	45 ^{+0.6}
TNH	49	97	6	69	1.5	91.5	≥ 65	≥ 115	45 ^{+0.6}	92 0
TNL	97	97	6	69	1.5	91.5	≥ 115	≥ 115	92 0.8	92+0.8

■ Bracket



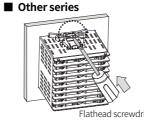




Installation Method

■ TNS

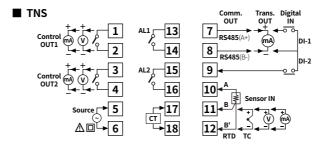


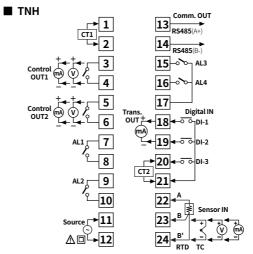


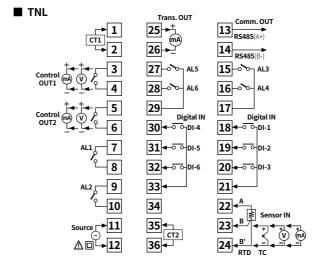
Insert the unit into a panel, fasten the bracket by pushing with tools with a flathead screwdriver.

Connections

 $\bullet \ \mathsf{Digital} \ \mathsf{input} \ \mathsf{is} \ \mathsf{not} \ \mathsf{electrically} \ \mathsf{insulated} \ \mathsf{from} \ \mathsf{internal} \ \mathsf{circuits}, \mathsf{so} \ \mathsf{it} \ \mathsf{should} \ \mathsf{be} \ \mathsf{insulated}$ when connecting other circuits.







Crimp Terminal Specifications

• Unit: mm, Use the crimp terminal of follow shape







Round crimp terminal

Initial Display When Power is ON

When power is supplied, after all display will flash for 1 sec, model name is displayed sequentially. After input sensor type will flash twice, enter into RUN mode.

Display part	1. Model	2. Model	3. Input specification	4. RUN mode
PV	Ł N 5.P	R5	£ YPE	oPEN
SV	42RR	006	K E R.H	0

Mode Setting Password Key input Entering mode Auto before entering to mode Password input when using [◀], [▲], [▼] Password input Fail assword) [MODE] Move digits: $[\blacktriangleleft]$ Change value: [▲], [▼] Save: When chage values $[\blacktriangleleft], [\blacktriangle], [\blacktriangledown]$ in manual control) Return: [MODE] or no key input over 3 sec Move digits: [◀] Change value: [▲], [▼] Save and Return: [MODE] or SV setting no key input over 3 sec Control output run/stop Operating value display part → RUN (MV / P/S /TM/CT) setting Shortcut key [**A**] 2 1/2/3 [◀] + [▼] 3 sec → **Key lock ON/OFF** Auto [M] 2 sec → Parameter group [◀] 2 sec U key enter [U] 2 sec parameter group → Parameter reset Refer to 'Parameter Reset'

Parameter Reset

- 01. Press the [◀] + [▲] + [▼] keys for over 5 sec. in run mode, INIT turns ON.
- 02. Change the setting value as YES by pressing the $[\blacktriangle]$, $[\blacktriangledown]$ keys.
- 03. Press the [M] key to reset all parameter values as default and to return to

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 $[\]bullet \, \mathsf{TNS} \, \mathsf{series} \, \mathsf{does} \, \mathsf{not} \, \mathsf{support} \, \mathsf{'MV} \, \mathsf{setting'}, \, \mathsf{'Operation} \, \mathsf{value} \, \mathsf{display} \, \mathsf{part} \, \mathsf{setting'} \, \mathsf{mode}. \, \mathsf{For} \, \mathsf{the} \, \mathsf{details}, \mathsf{refer} \, \mathsf{to} \, \mathsf{the} \, \mathsf{details}, \, \mathsf{value} \, \mathsf{display} \, \mathsf{part} \, \mathsf{setting'} \, \mathsf{mode}. \, \mathsf{For} \, \mathsf{the} \, \mathsf{details}, \, \mathsf{refer} \, \mathsf{to} \, \mathsf{the} \, \mathsf{details}, \, \mathsf{th$